



Incidentalità stradale in Lombardia

Corso di Formazione: Elementi di geo-statistica e microsimulazione spaziale
25 Giugno 2024

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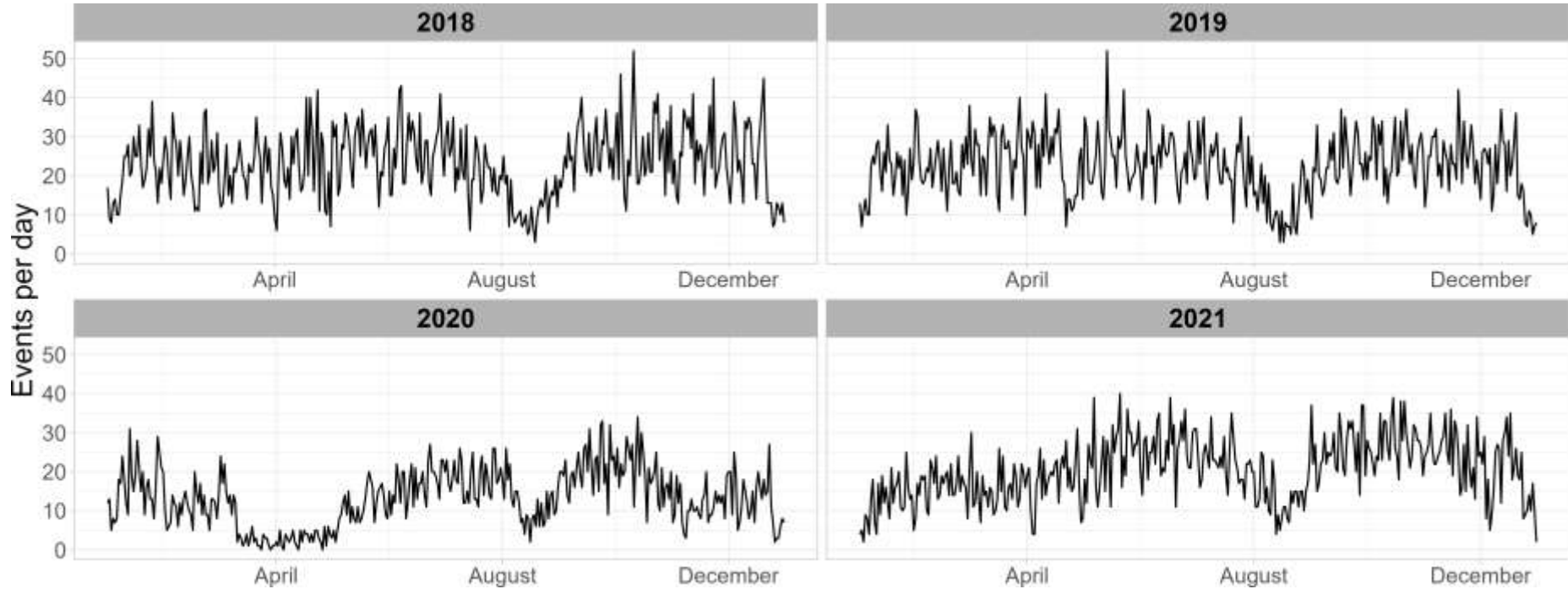
Goals:

- Introduce a series of **statistical methods** to describe and analyse road accident data.
- **Explore** the spatio-temporal car crashes **hotspots** in Milan and on Via Olimpica, years 2018 - 2021.
- Pinpoint areas and periods of **high incidence**, examining the **safety patterns**' variations along the years.

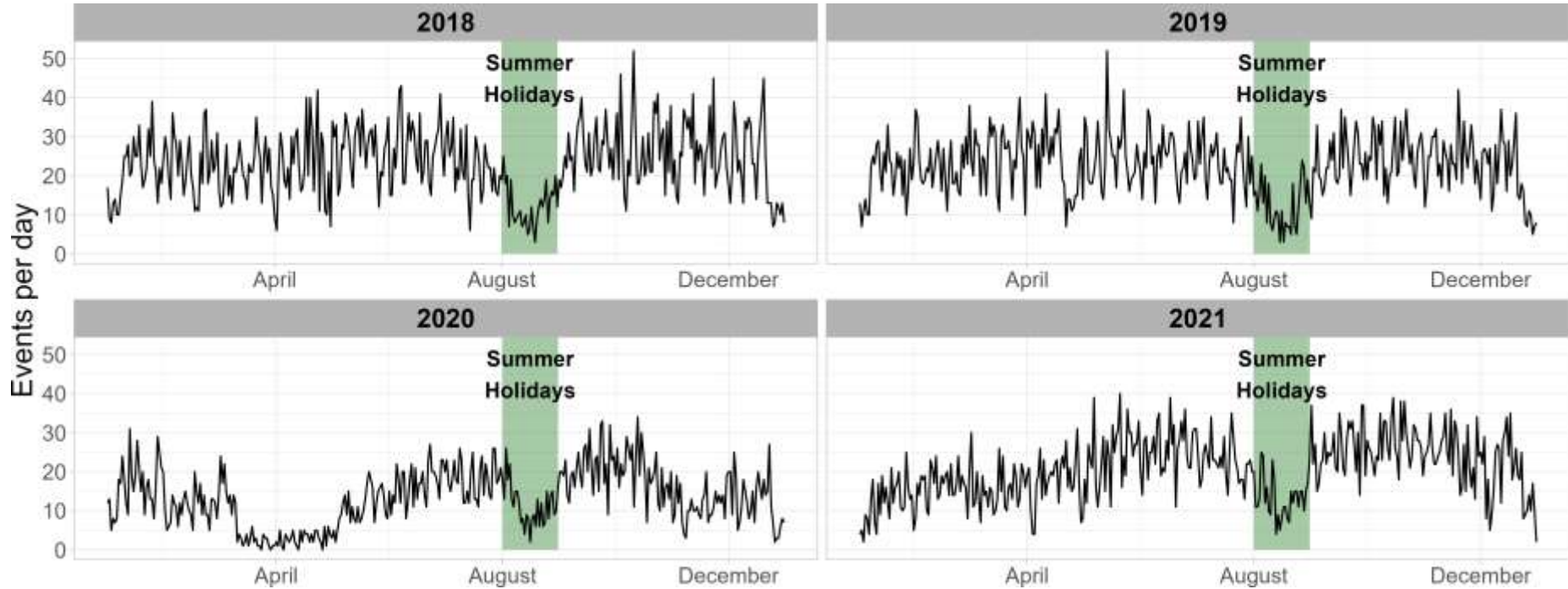
	Spatial domain	Temporal domain	Sources
Car crashes		2018 - 2021	
Ambulance interventions		2018 - 2020	
Open Street Map		Continuous updates	

Spatio-temporal analysis - Milan

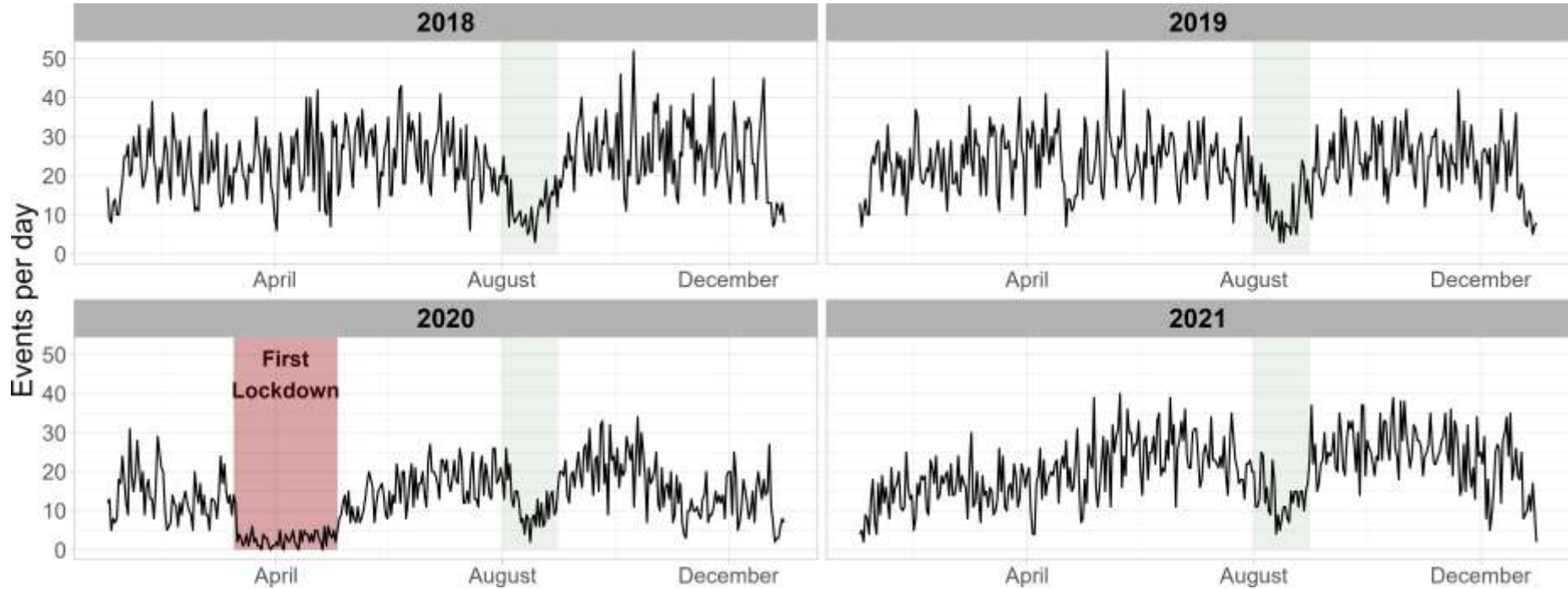
Temporal analysis - Milan



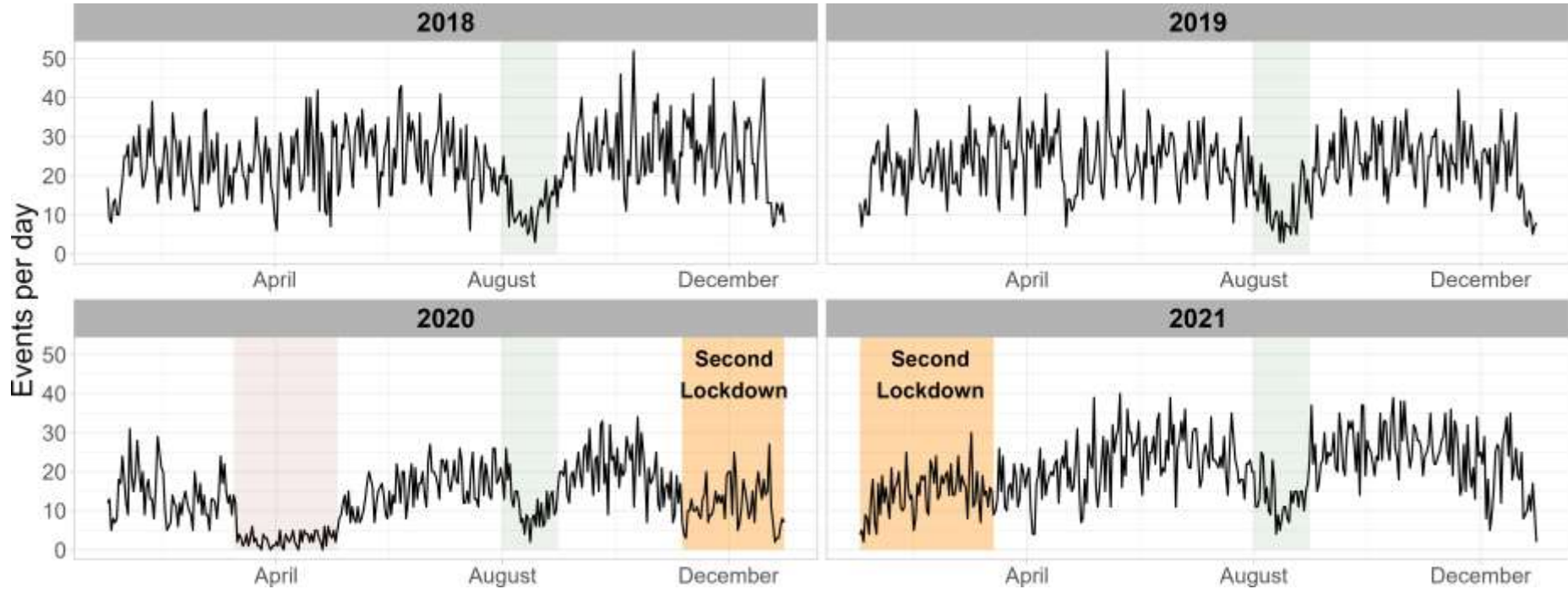
Temporal analysis - Milan



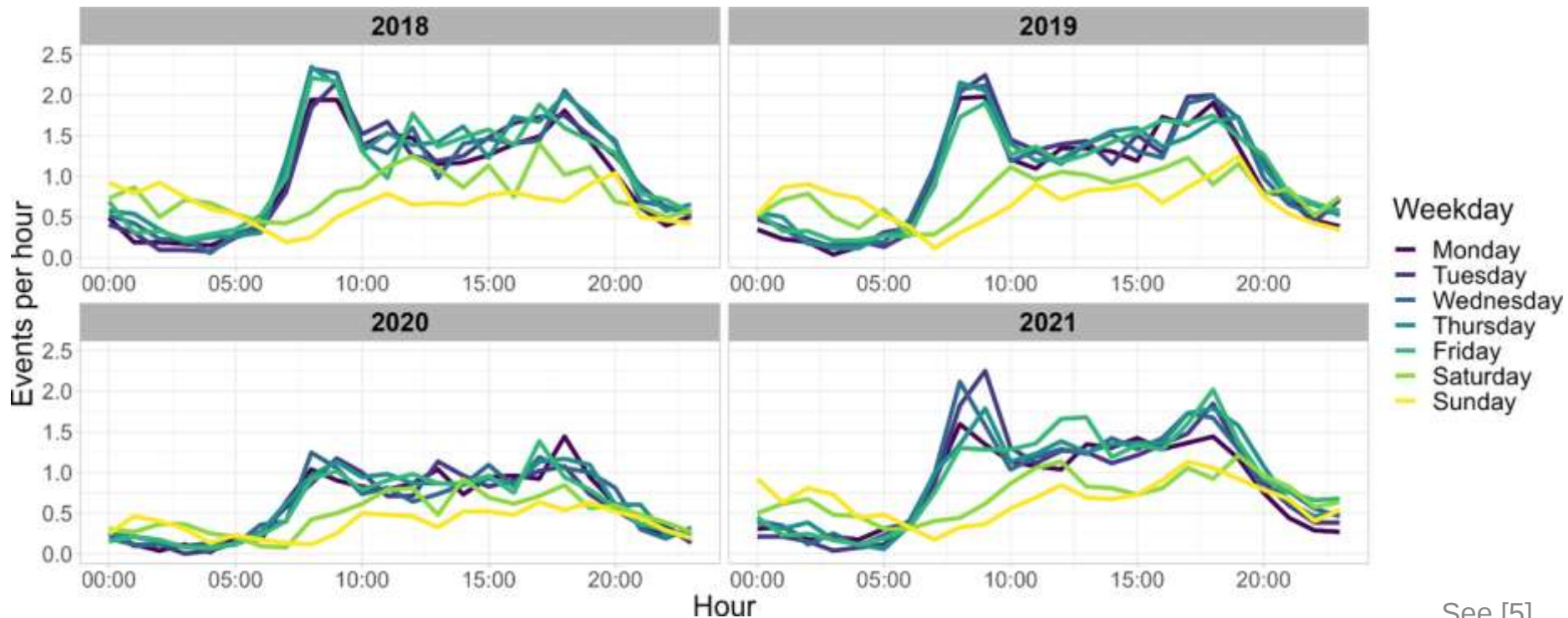
Temporal analysis - Milan



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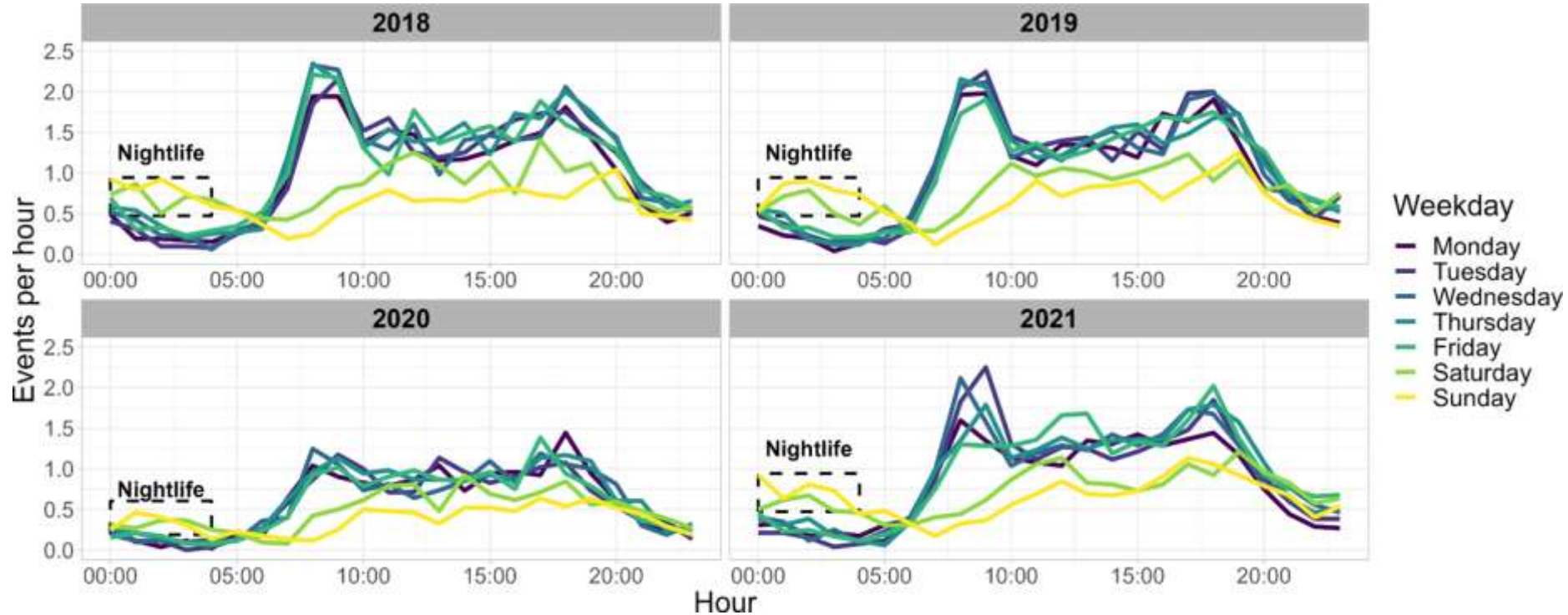


Temporal analysis - Milan

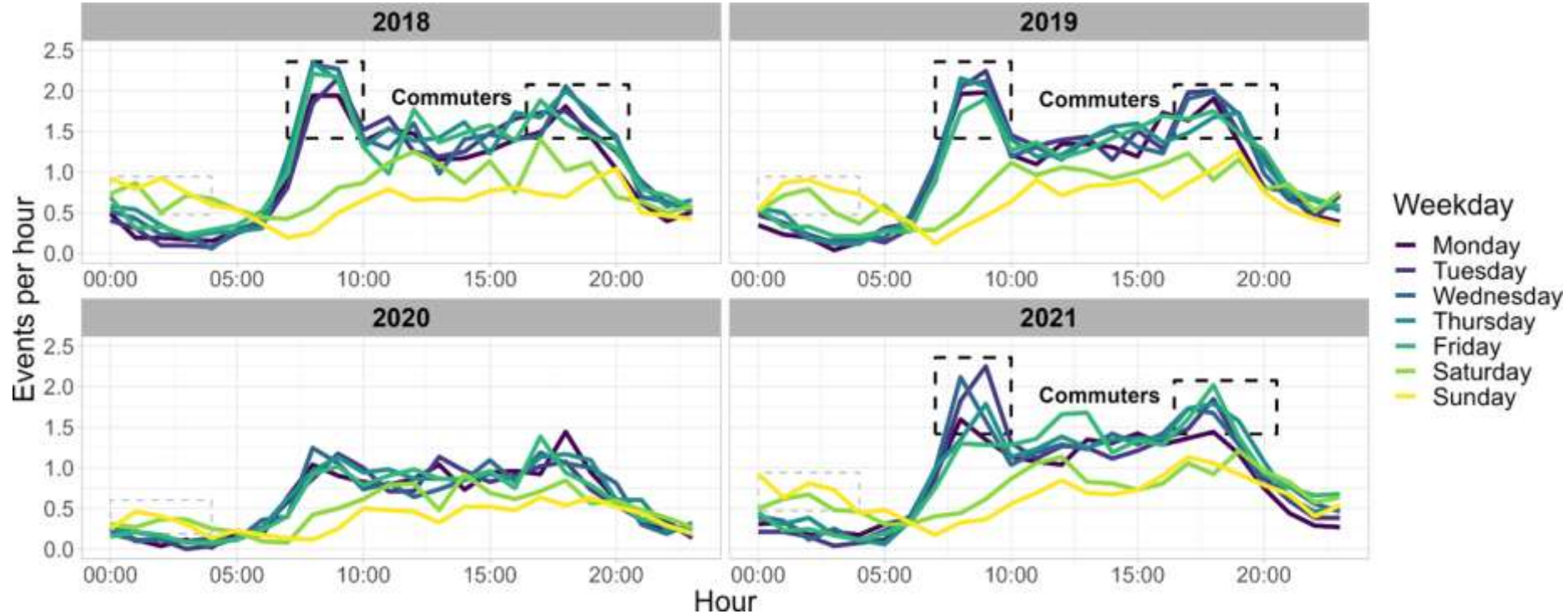


See [5]

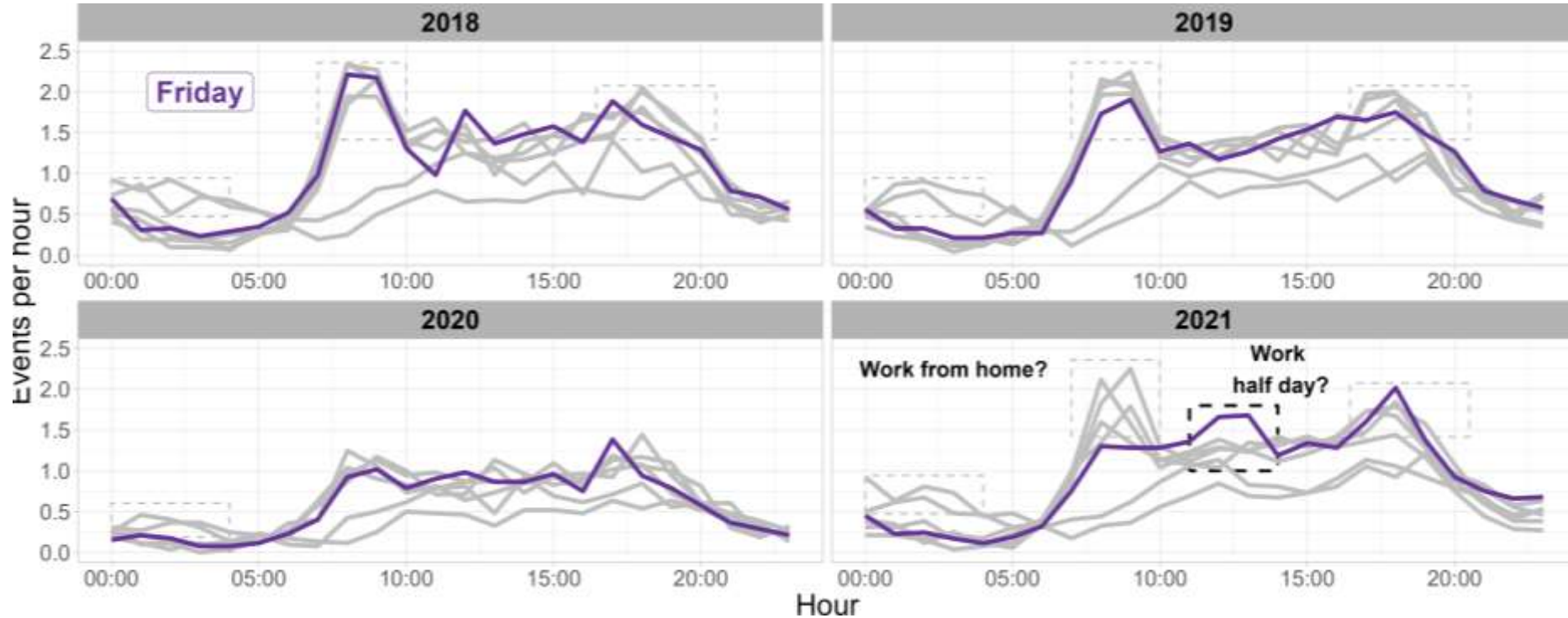
Temporal analysis - Milan



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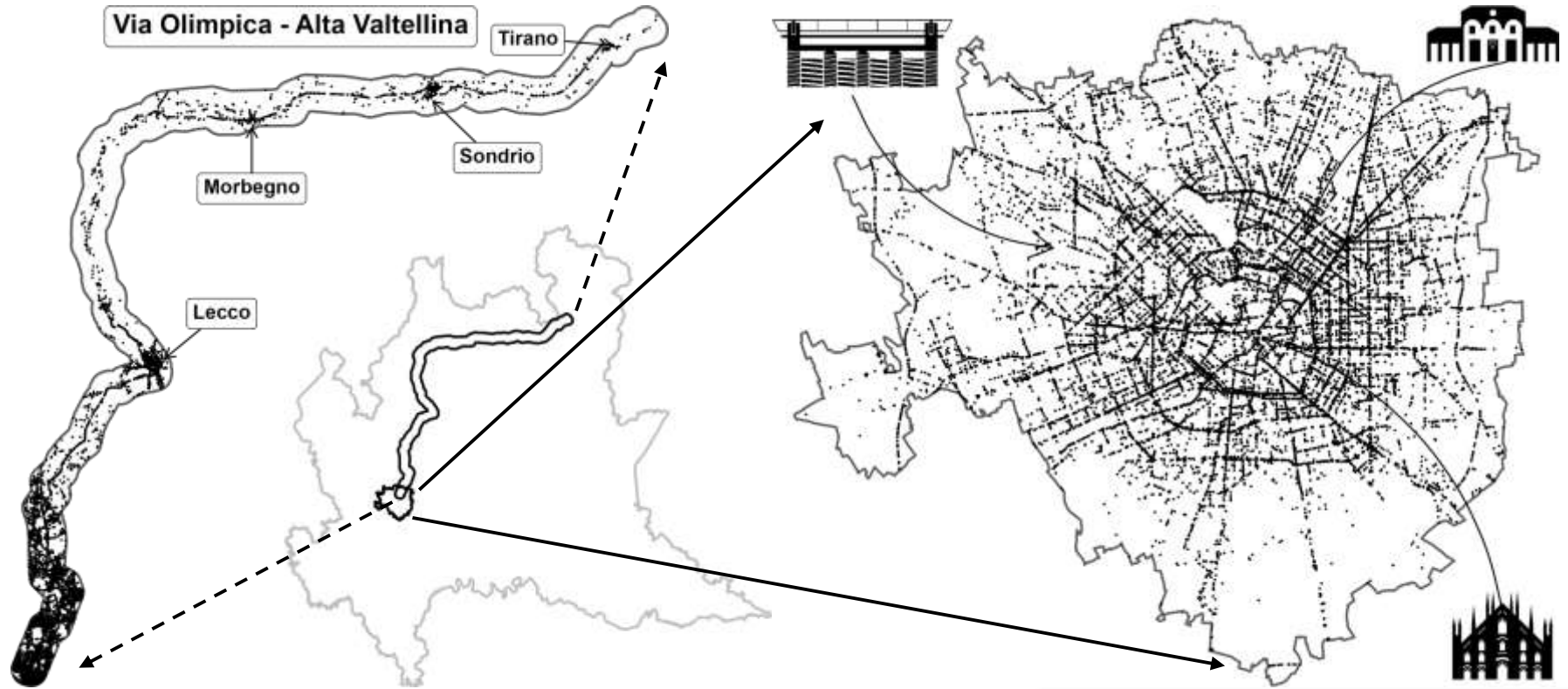
1. Weekly seasonal effects due to **summer holidays** in August, which are also present in 2020 and 2021
2. **Drastic reductions** due to COVID-19 lockdowns
3. Hourly seasonal components linked to **nightlife** and **commuters** are clearly evident in 2018, 2019, and 2021.

4. These hourly patterns are **almost absent** in 2020

5. Nevertheless, the behaviour on **friday** during 2021 is substantially different from 2018 and 2019.

Work-from-home policies adopted
by large firms near Milan?

Spatial representation



Road accidents represent a classic example of **spatial point patterns**: sets of **points** placed inside an **observation window (W)**

Typical statistical analyses involve:

1. Detection of spatial trends/**hotspots**;
2. Identification of **clustering behaviours**
3. Exploring the relationship with **external covariates** (e.g. the road type)



- Given a spatial point pattern $X = \{x_1, \dots, x_n\}$, we can define its **intensity** function $\lambda(s), s \in W$ as

Intensity function
at location $s \in W$

$\lambda(s)$

$$\lambda(s) = \lim_{|d(s)| \rightarrow 0} \frac{\mathbb{E}[N(d(s))]}{|d(s)|}$$

Expected number of
events in proximity of s

Area of a region
surrounding s

- $\lambda(s)$ represents the **expected number of events** per unit area that we may observe in **proximity** of s
- When $\lambda(s)$ is **constant** for all $s \in W$, we say that the pattern is **homogeneous**, otherwise it's **inhomogeneous**
- We can define the **density** of X as a **normalised** intensity:

$$f(s) = \frac{\lambda(s)}{n}$$

- The usual (non-parametric) **estimator** of the intensity function for a (planar) point pattern is:

The estimate of $\lambda(s)$

$$\hat{\lambda}(s) = \frac{1}{e(s)} \sum_{i=1}^n K(s, x_i, h)$$

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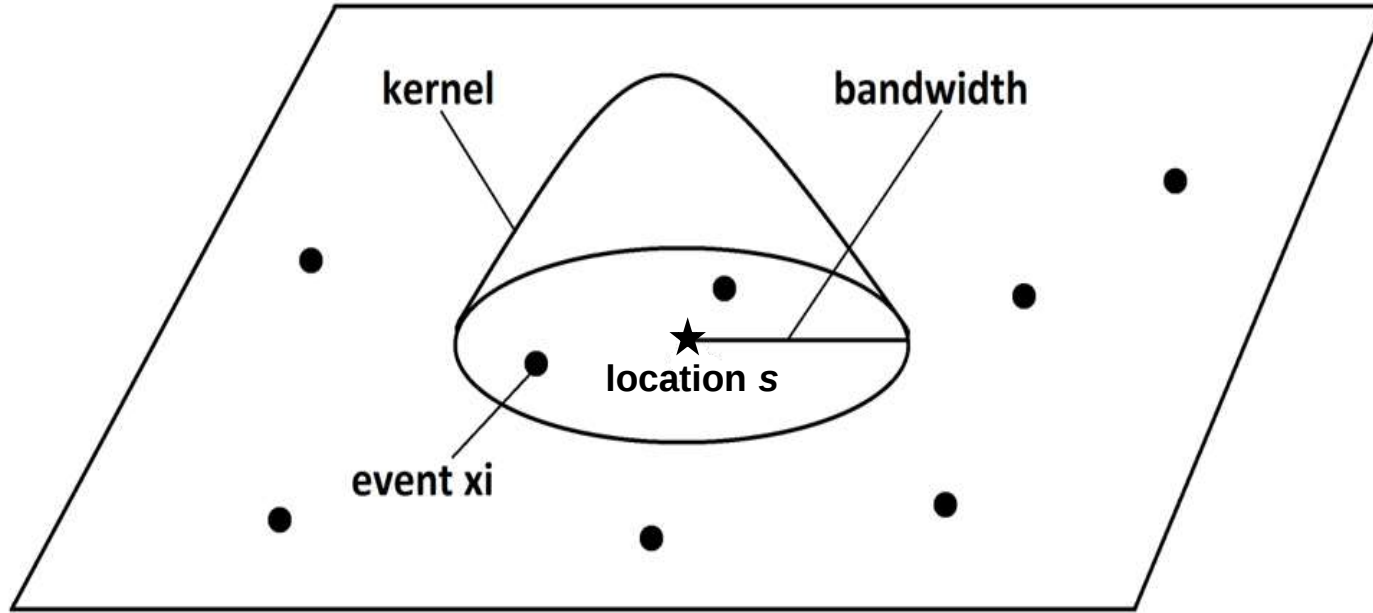
$$\hat{\lambda}(s) = \frac{1}{e(s)} \sum_{i=1}^n K(s, x_i, h)$$

An edge-correction term

$K(\cdot)$ is a kernel function (i.e. an arbitrary density function)

h is a smoothing parameter known as *bandwidth*

Graphical representation of the estimation process



Courtesy of
Moraga (2023)

- Nevertheless, car crashes represent a classic example of **point patterns on a linear network (L)**
- A proper spatial analysis must always consider the **spatial domain** of the data...



- Therefore, we need to **correct** the usual estimator:

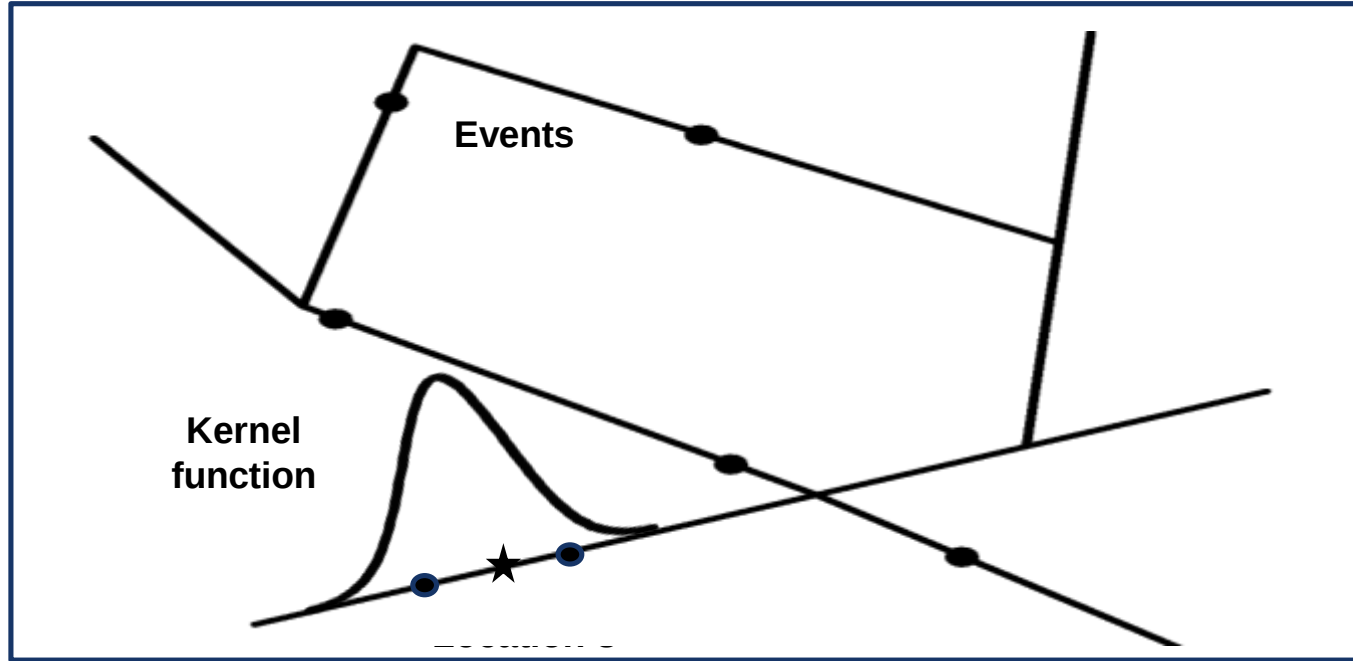
The network-corrected estimate of $\lambda(s)$

The Kernel function (same as before)

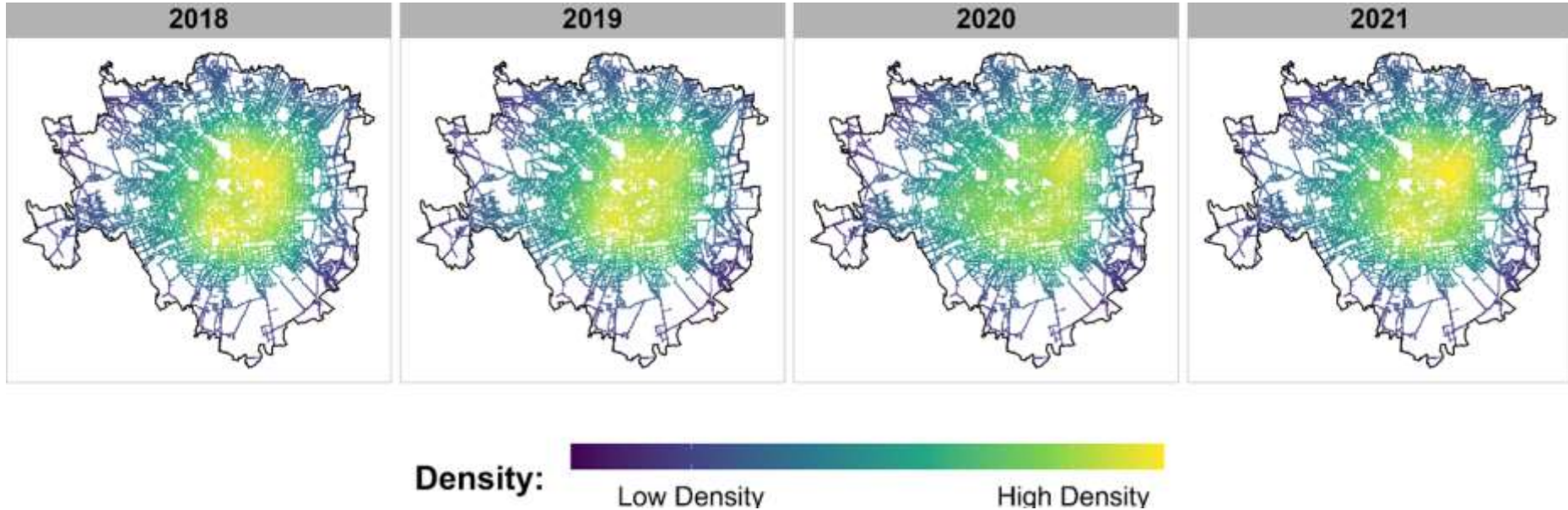
$$\widehat{\lambda}_L(s) = \frac{1}{e(s)} \sum_{i=1}^n \frac{K(s, x_i, h)}{c_L(s)}$$

A linear-network correction term

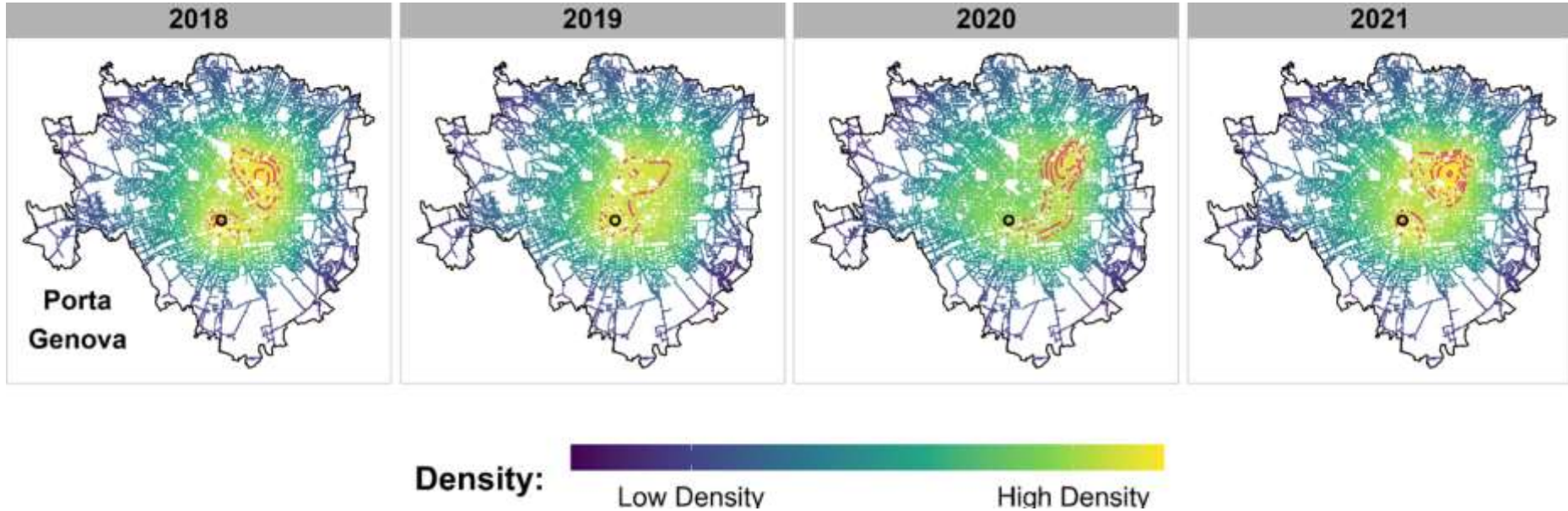
Graphical representation of the estimation process



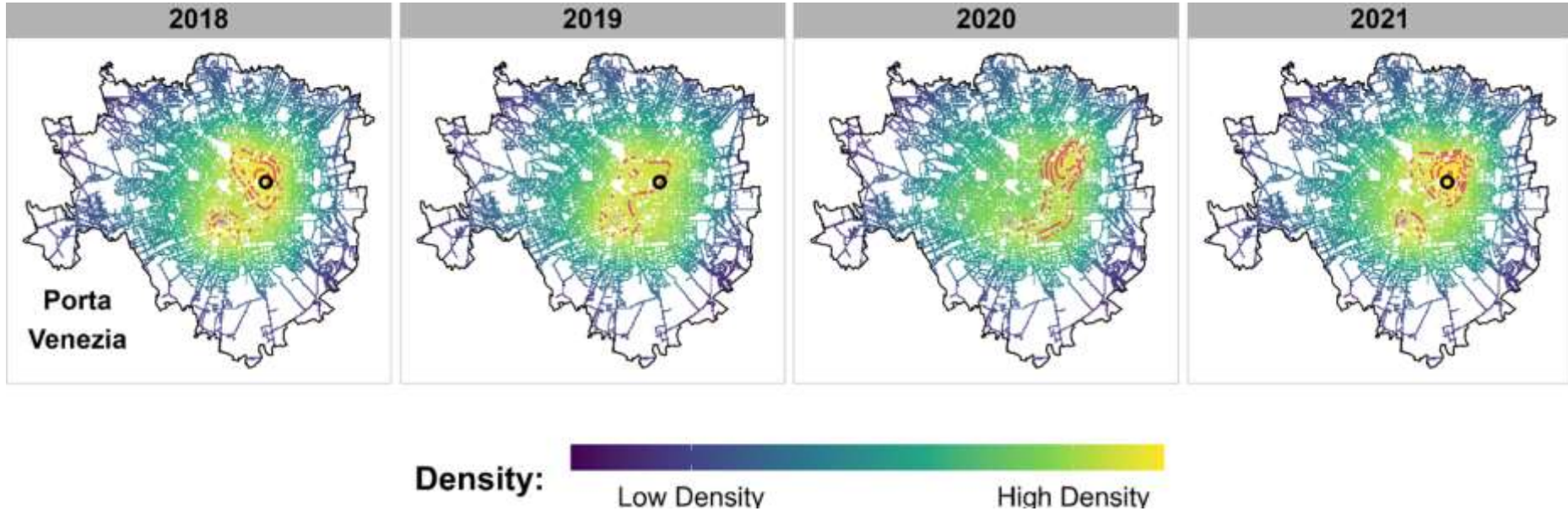
Smoothed density of car crashes



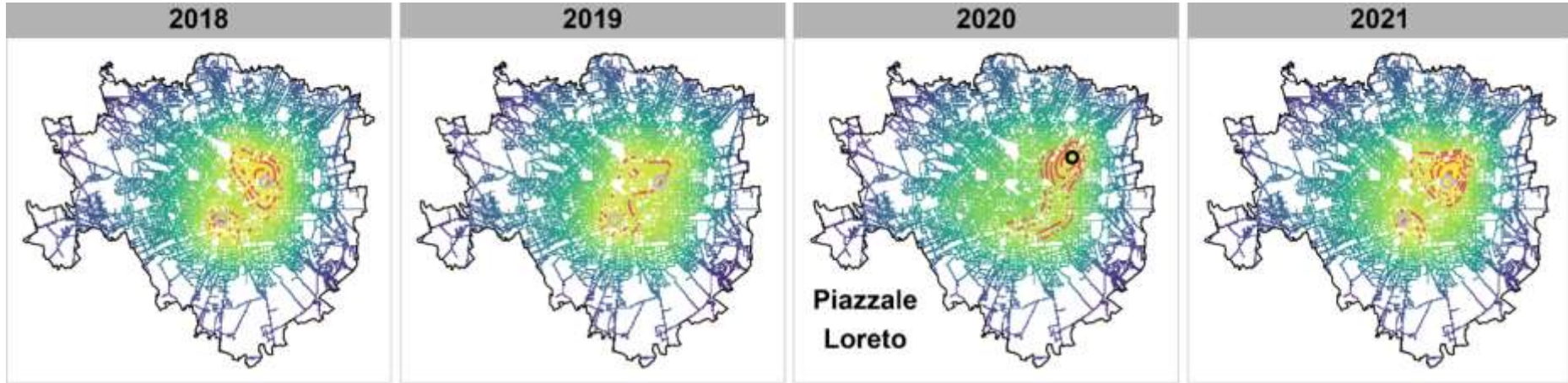
Smoothed density of car crashes



Smoothed density of car crashes



Smoothed density of car crashes



Density:



Infrastructural Problems ?

- The **spatial relative risk**, $\rho(s)$, is a statistical technique to compare two point-patterns observed at **different times**.
- It can be mathematically defined as:

$$\widehat{\rho}_t(s) = \frac{\widehat{f}_t(s)}{\widehat{f}_t(s) + \widehat{f}_{2018}(s)}$$

Estimate of the spatial relative risk (pointing to $\widehat{\rho}_t(s)$)

Spatial density during year t (pointing to $\widehat{f}_t(s)$)

Spatial density during a reference year (2018) (pointing to $\widehat{f}_{2018}(s)$)

Interpretation:

$$\widehat{\rho}_t(s) = \frac{\widehat{f}_t(s)}{\widehat{f}_t(s) + \widehat{f}_{2018}(s)}$$

$$\widehat{\rho}_t(s) \simeq 0 \Rightarrow \widehat{f}_t(s) \ll \widehat{f}_{2018}(s)$$

The car crashes' density during year t at location s is **much smaller** than during 2018

Interpretation:

$$\widehat{\rho}_t(s) = \frac{\widehat{f}_t(s)}{\widehat{f}_t(s) + \widehat{f}_{2018}(s)}$$

$$\widehat{\rho}_t(s) \simeq 0.5 \Rightarrow \widehat{f}_t(s) \simeq \widehat{f}_{2018}(s)$$

The car crashes' density during year t at location s is **almost the same as** during 2018

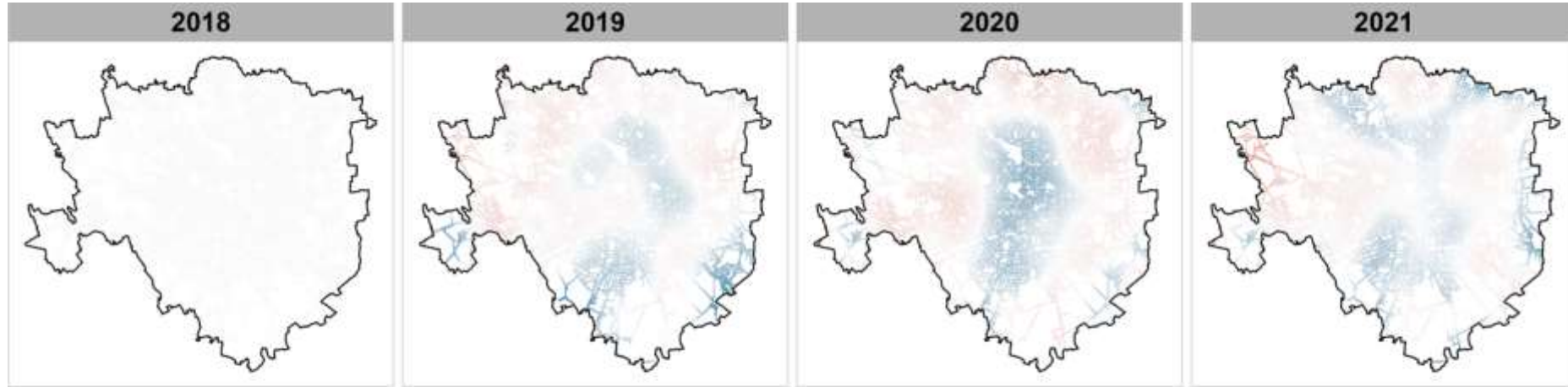
Interpretation:

$$\widehat{\rho}_t(s) = \frac{\widehat{f}_t(s)}{\widehat{f}_t(s) + \widehat{f}_{2018}(s)}$$

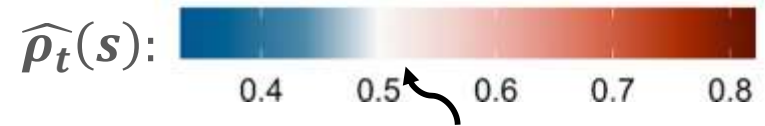
$$\widehat{\rho}_t(s) \simeq 1 \Rightarrow \widehat{f}_t(s) \gg \widehat{f}_{2018}(s)$$

The car crashes' density during year t at location s is **much larger** than during 2018

Ratio of spatial densities



$$\widehat{\rho}_t(s) = \frac{\widehat{f}_t(s)}{\widehat{f}_t(s) + \widehat{f}_{2018}(s)}$$



| = Equal Densities

See [1, 2, 4]

1. During 2018, 2019, and 2021, the hotspots are located in proximity of **Porta Genova** and **Porta Venezia**.
2. We notice a **peak** of events near **Piazzale Loreto** during 2020.
3. The density-ratio maps showcase a reduction of car crashes density near the city centre in 2020, possibly due to the **lower traffic volumes**.

- Let $X = \{x_1, \dots, x_n\}$ be a point pattern and let $\lambda(s)$ denote its intensity function
- We can also relate $\lambda(s)$ to one or more fixed variables (e.g the road type). For example:

$$\lambda(s) = \lambda(s; \theta) = \exp(\theta_0 Z_0 + \theta_1 Z_1 + \dots + \theta_p Z_p)$$

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**Unknown coefficients
(to be estimated)**



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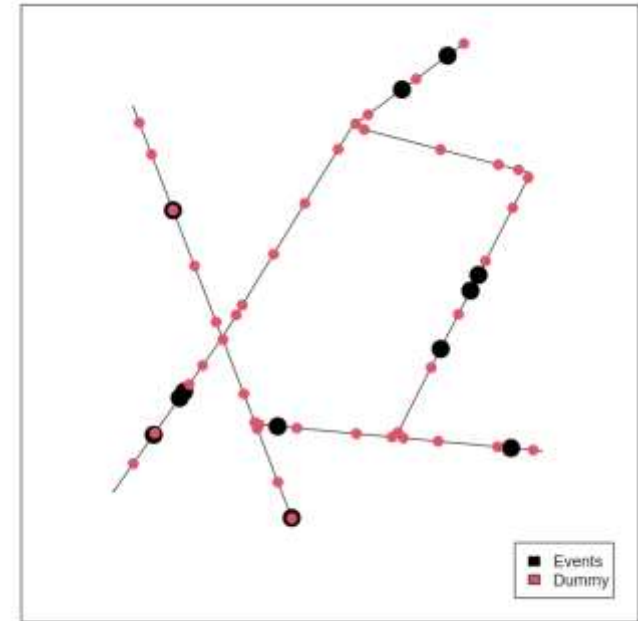
$$\lambda(s) = \lambda(s; \theta) = \exp(\theta_0 Z_0 + \theta_1 Z_1 + \dots + \theta_p Z_p)$$

Unknown coefficients
(to be estimated)

Known spatial functions



- The coefficients are estimated employing a techniques known as Berman Turner device:
 - Simulate a set of **dummy points** and *superimpose* them to the events
 - Compute a **weight** for each point after **splitting** the network into smaller parts
 - Calculate the Z_p value in **each segment** and sum the weights
 - Estimate $\theta_1, \dots, \theta_p$ using standard **GLM** techniques



Deep dive on car crashes and road types

- According to a recent [report](#) shared by PoliS: “La categoria di strada più a rischio incidentalità, lesività, e mortalità è quella delle **strade urbane** (di Regione Lombardia) dove si concentra il 76,9% di incidenti, il 49,9% di morti e il 73,7% di feriti.”

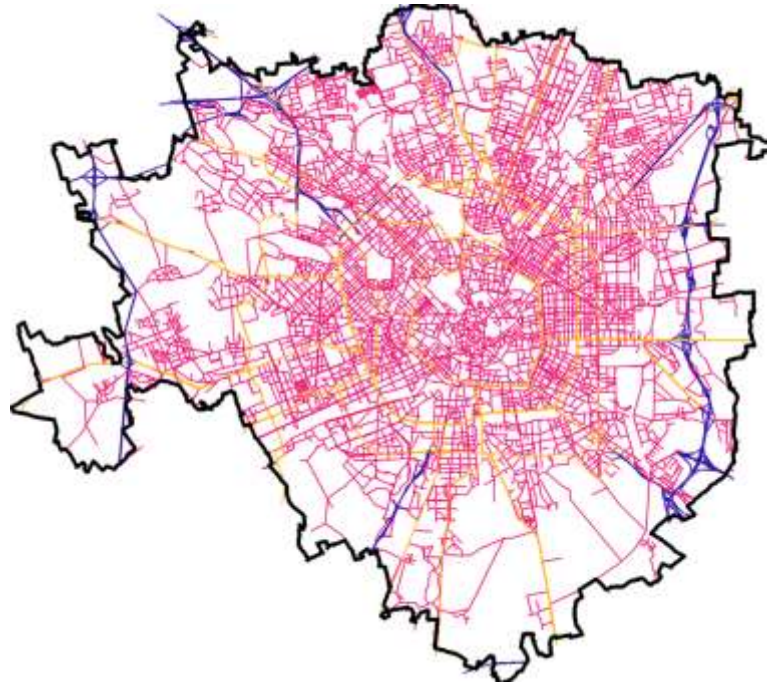
CATEGORIA STRADA	Incidenti	Morti	Feriti	Indice mortalità	Var.% incidenti 2020-2021	Var.% morti 2020-2021	Var.% feriti 2020-2021
Strade urbane ^(a)	19.860	178	24.807	0,9	29,3%	20,3%	29,2%
Autostrade	1.474	32	2.275	2,2	51,0%	6,7%	53,4%
Altre strade ^(b)	4.504	147	6.590	3,3	24,0%	5,8%	25,3%
TOTALE	25.838	357	33.672	1,4	29,4%	12,6%	29,8%

(a) Sono incluse nella categoria “Strade urbane” anche le Provinciali, Statali e Regionali entro l’abitato.

(b) Sono incluse nella categoria “Altre strade”, le strade Statali, Regionali e Provinciali fuori dall’abitato e Comunali extraurbane.

Deep dive on car crashes and road types

We used two types of **parametric Poisson regression model** to further explore these findings.



Autostrade o Superstrade

Strade locali

Strade Statali e Provinciali

Deep dive on car crashes and road types

Ratio of car accident rates (Reference year: 2018)

2019	2020	2021
0.97 (0.95; 1.00)	0.57 (0.55; 0.60)	0.88 (0.86; 0.91)

Interpretation: On average, the number of car crashes per metre observed in 2020 is **57%** of that observed in 2018. The 95% confidence interval is (0.55; 0.60).

Deep dive on car crashes and road types

Ratio of car accident rates (Reference category: Autostrade)

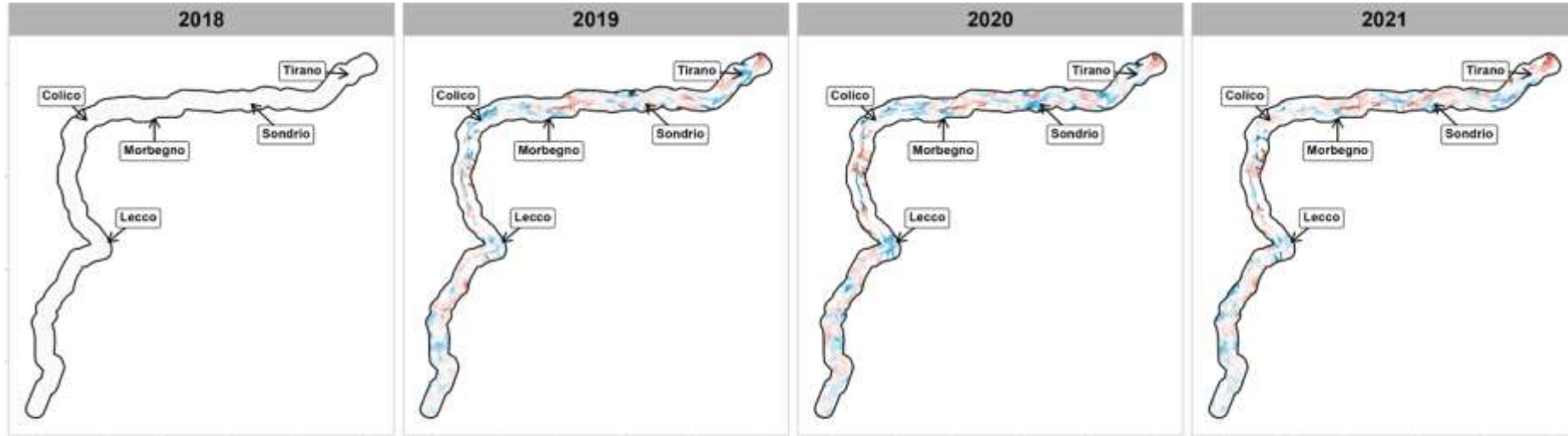
	2018	2019	2020	2021
Strade Locali	1.32 (1.19; 1.46)	1.32 (1.18; 1.46)	1.58 (1.37; 1.83)	1.44 (1.28; 1.62)
Strade Statali e Provinciali	3.83 (3.44; 4.26)	3.70 (3.32; 4.12)	4.26 (3.66; 4.96)	4.08 (3.62; 4.59)

Interpretation: On average, the number of car crashes per metre observed in 2020 on *Strade Statali e Provinciali* is **426%** of that observed in *Autostrade e Superstrade* during the same year. The 95% confidence interval is (3.66; 4.96).

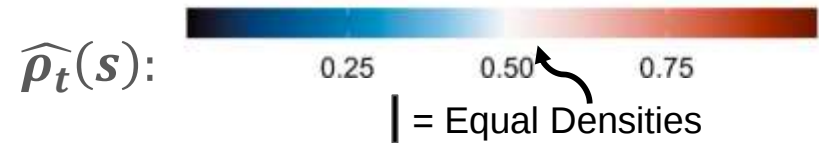
1. The statistical models let us **reproduce** and **replicate** the findings detailed in the report shared by **Polis**.
2. We can notice that, on average, *Strade Statali* is much **more dangerous** than *Autostrade* or *Superstrade*.
3. These effects do not seem to be stationary along the years.

Spatio temporal analysis - Via Olimpica

Ratio of spatial densities

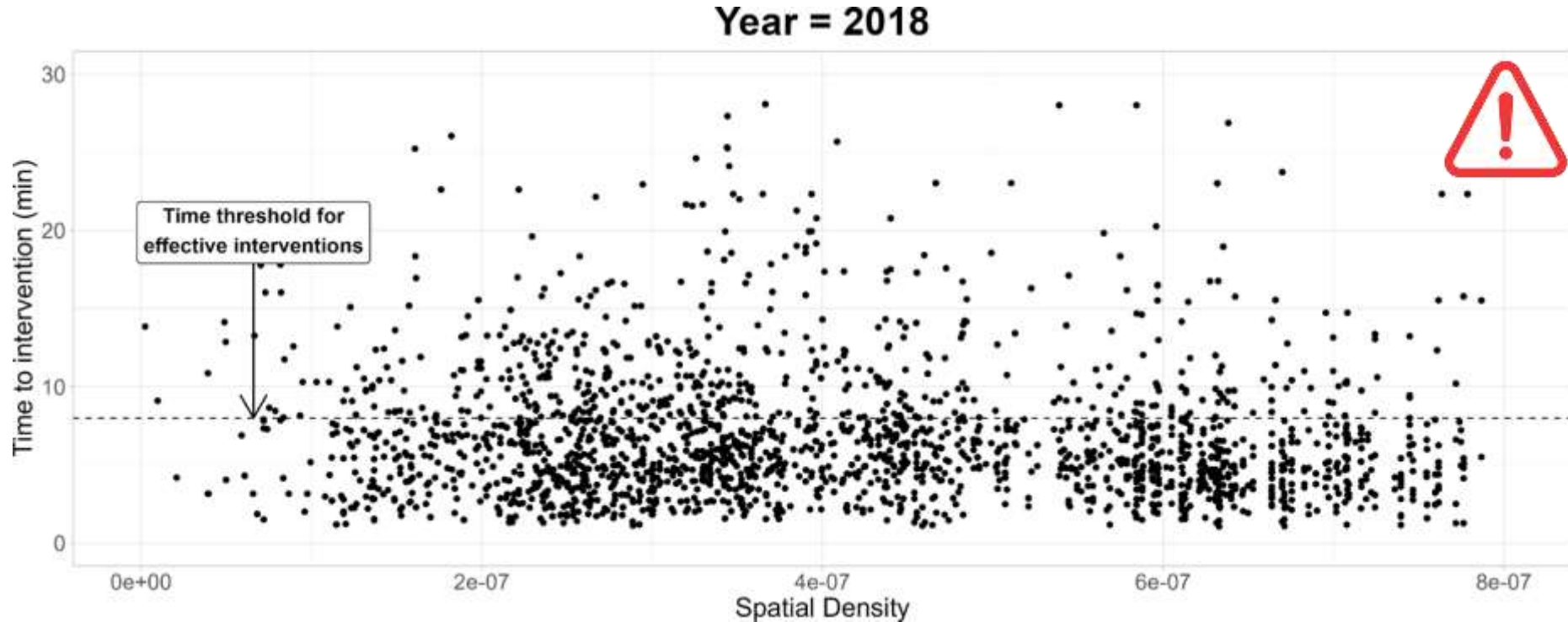


$$\widehat{\rho}_t(s) = \frac{\widehat{f}_t(s)}{\widehat{f}_t(s) + \widehat{f}_{2018}(s)}$$

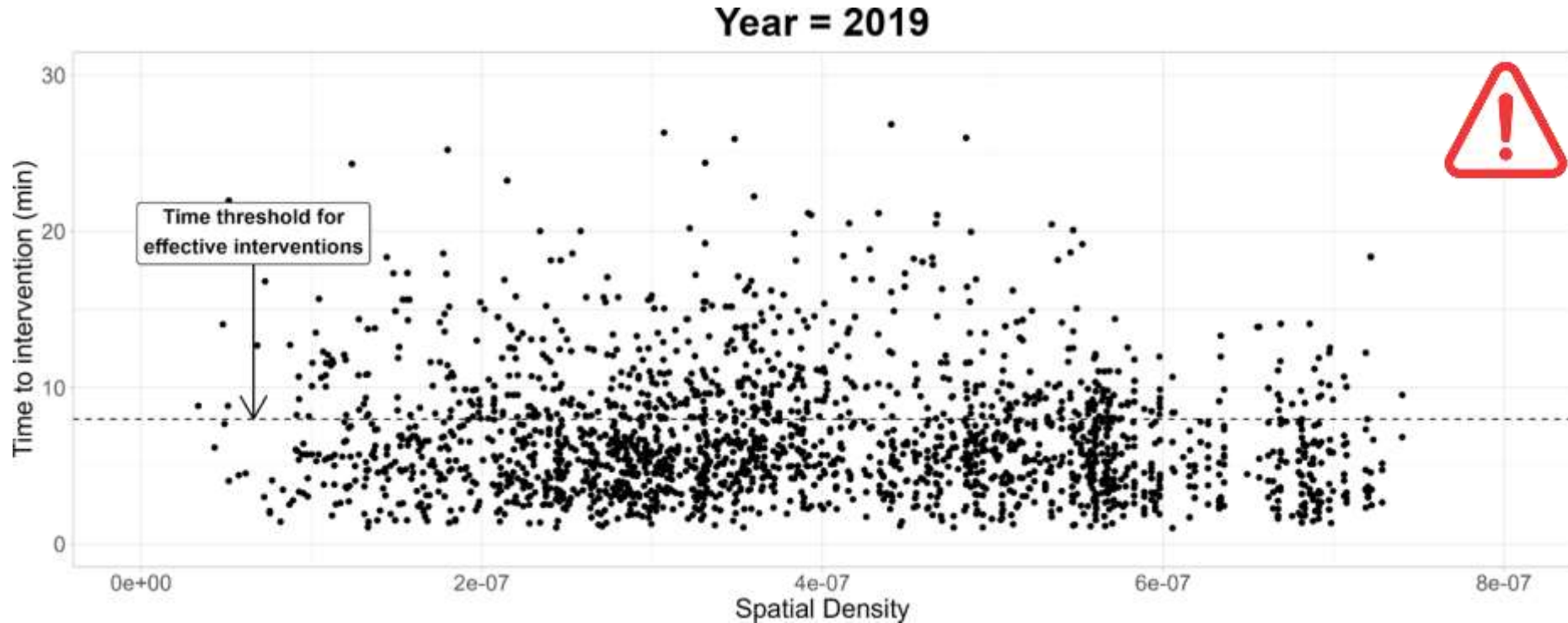


- First, we **merged** the car crashes data with the database of ambulance interventions using a **spatial matching operation**.
- Then, we derived an index that represents the **time** required for the first ambulance to **arrive at the location of the car crash**.

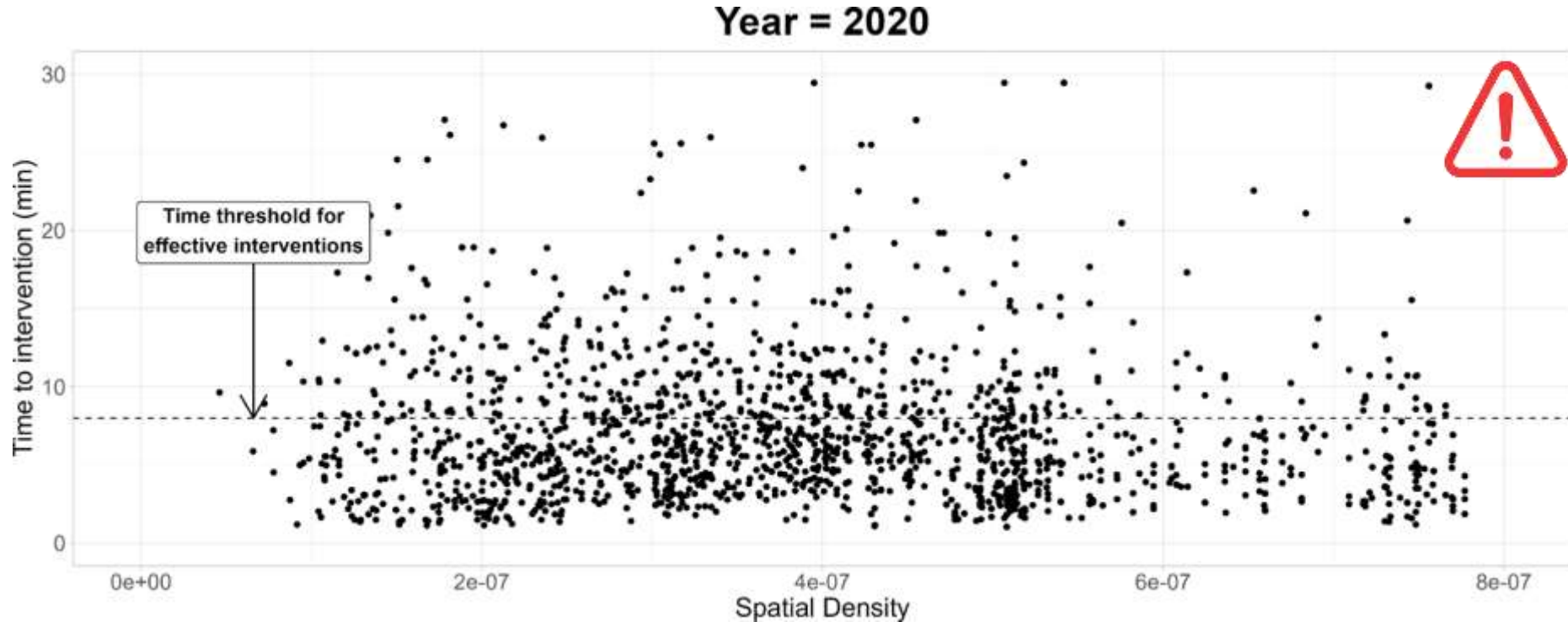
Spatial densities and time to intervention



Spatial densities and time to intervention



Spatial densities and time to intervention



1. The spatial ratios appear quite **stable** in the **first half of Via Olimpica**, from Milan to Colico.
2. There are slightly **more pronounced** differences in **Alta Valtellina**, especially near Morbegno or Sondrio.
3. During 2018, several crashes occurred in **proximity of an hotspot** and required **more than 8 minutes** to get an ambulance intervention.

4. The situation is **remarkably better** in 2019!
5. Unfortunately, the **performances** of the ambulance intervention system **get worse** during 2020.
6. Integrating **PoliS** and **AREU** data let us identify risky areas where we could **optimise** the ambulance response times through **reallocation** algorithms.

• Estimation of road traffic to measure the exposure [7].	 An icon representing a carpool lane. It shows three cars in the left lane and two cars in the right lane, separated by a dashed line. The right lane is shaded with diagonal lines.
• Development of marked point process models for multivariate estimation of safety indices.	 An icon representing a marked point process model. It shows a green line graph with a series of green dots scattered above it, indicating data points over time or space.

Acknowledgments



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Ministero
dell'Università
e della Ricerca



Italiadomani
Piano Nazionale
di Ripresa e Resilienza



GRINS
FOUNDATION

This study was carried out within the [GRINS: Growing Resilient, INclusive and Sustainable](#) project, which is part of the Next Generation EU program (National Recovery and Resilience Plan).



POLITECNICO
DI MILANO



Seminal and review papers:

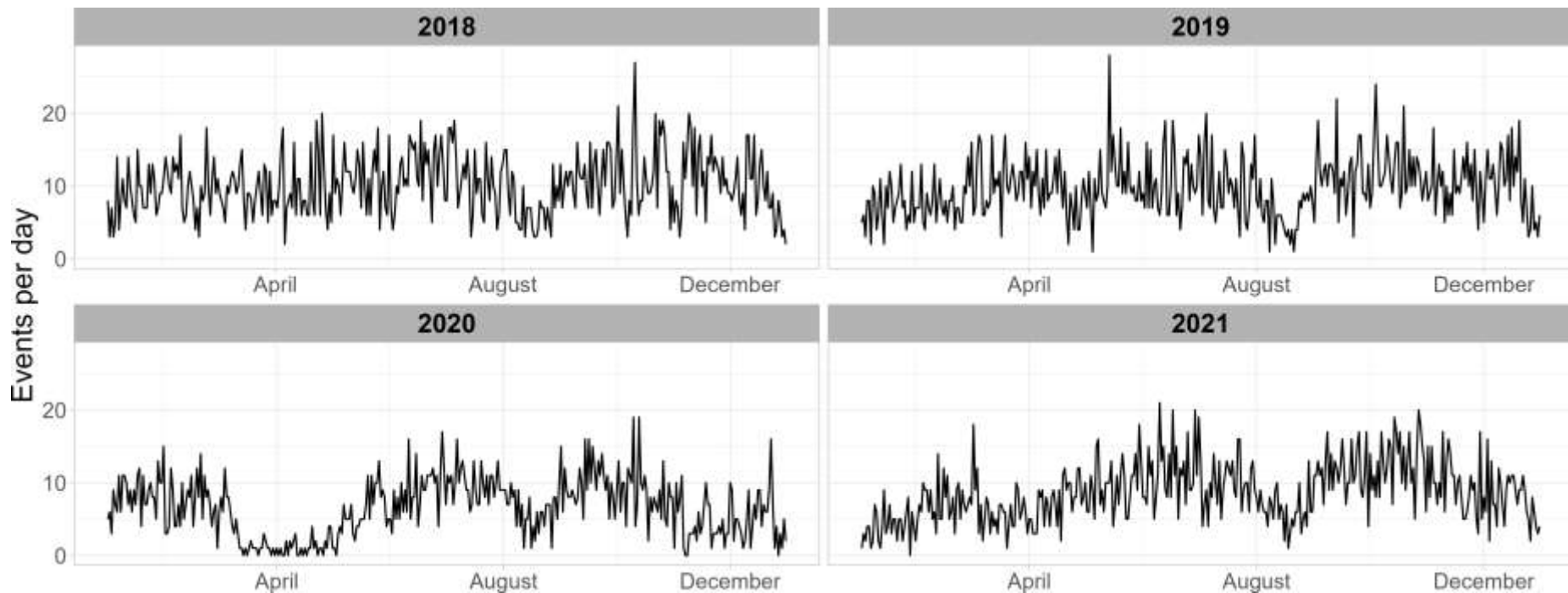
- [1] Kelsall, J. E., & Diggle, P. J. (1995). Non-parametric estimation of spatial variation in relative risk. *Statistics in medicine*, 14(21-22), 2335-2342.
- [2] McSwiggan, G., Baddeley, A., & Nair, G. (2020). Estimation of relative risk for events on a linear network. *Statistics and Computing*, 30, 469-484.
- [3] Rakshit, S., Davies, T., Moradi, M. M., McSwiggan, G., Nair, G., Mateu, J., & Baddeley, A. (2019). Fast kernel smoothing of point patterns on a large network using two-dimensional convolution. *International Statistical Review*, 87(3), 531-556.

State of the art:

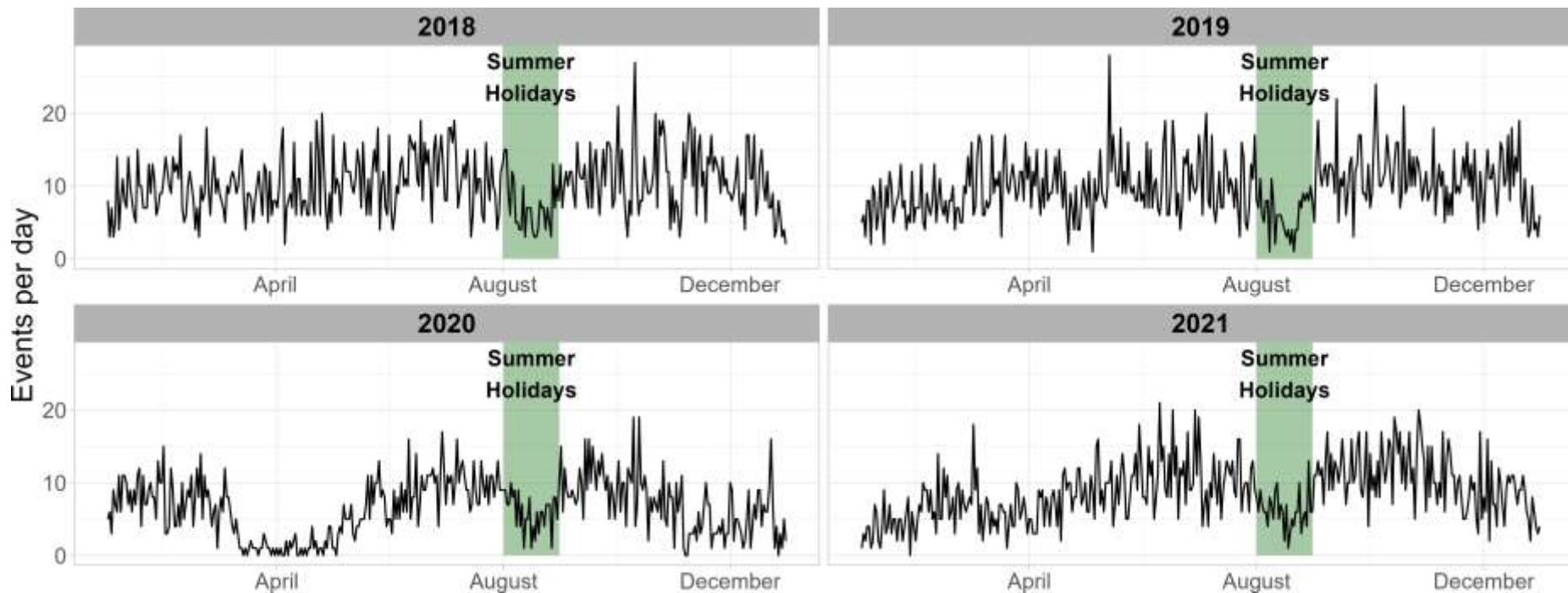
- [4] Baddeley, Adrian, Gopalan Nair, Suman Rakshit, Greg McSwiggan, and Tilman M. Davies. "Analysing point patterns on networks—A review." *Spatial Statistics* 42 (2021): 100435.
- [5] Gilardi, A., Borgoni, R., Mateu, J. (2023+) A non-separable first-order spatio-temporal intensity for events on linear networks: an application to ambulance interventions. Accepted for publication in *Annals of Applied Statistics*.
- [6] Ferraccioli, F., Arnone, E., Finos, L., Ramsay, J. O., & Sangalli, L. M. (2021). Nonparametric density estimation over complicated domains. *Journal of the Royal Statistical Society Series B: Statistical Methodology*, 83(2), 346-368.
- [7] Gilardi, A., Borgoni, R., Presicce, L., & Mateu, J. (2023). Measurement error models for spatial network lattice data: Analysis of car crashes in Leeds. *Journal of the Royal Statistical Society Series A: Statistics in Society*, 186(3), 313-334.

Appendix: Temporal analysis along Via Olimpica

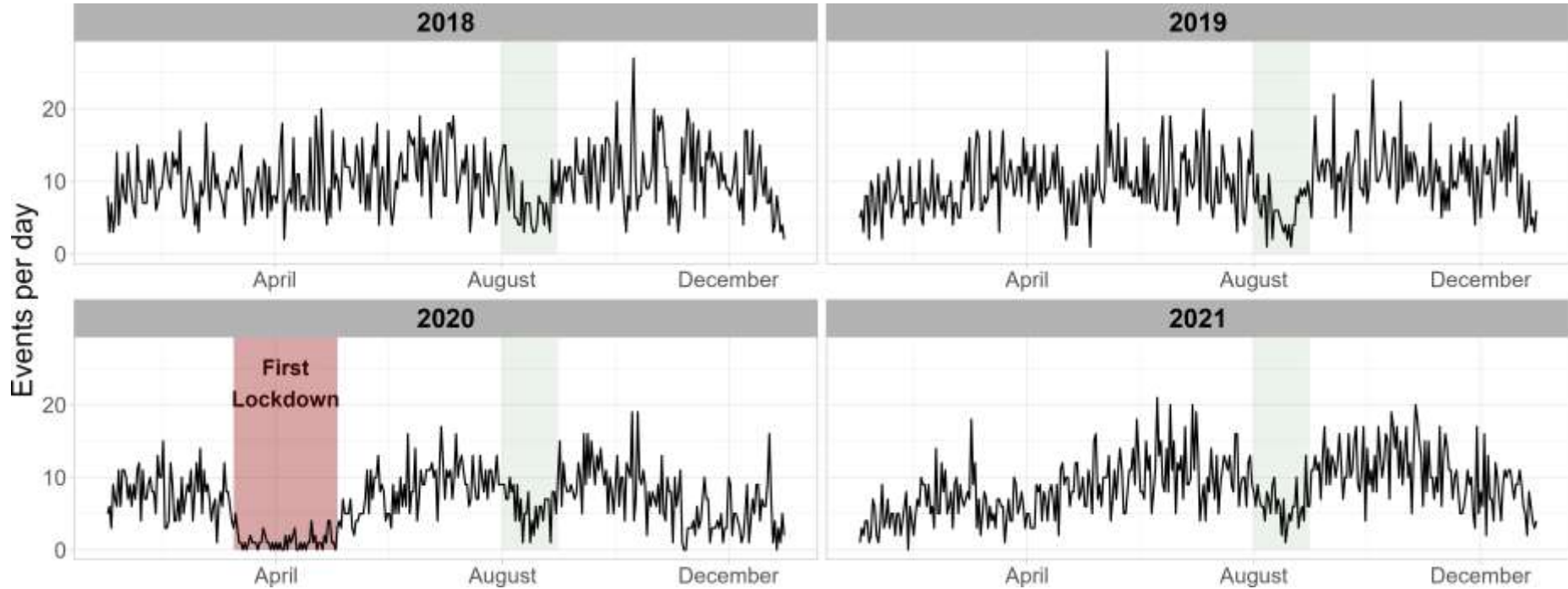
Temporal analysis - Via Olimpica



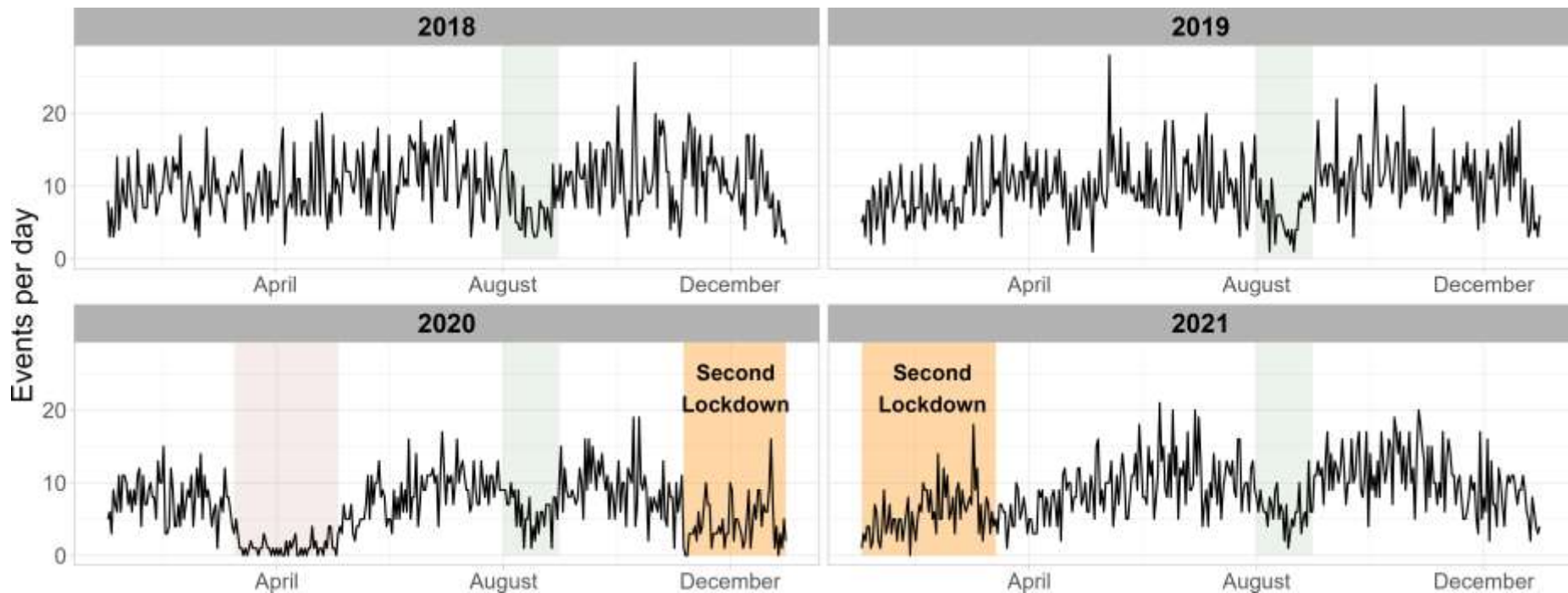
Temporal analysis - Via Olimpica



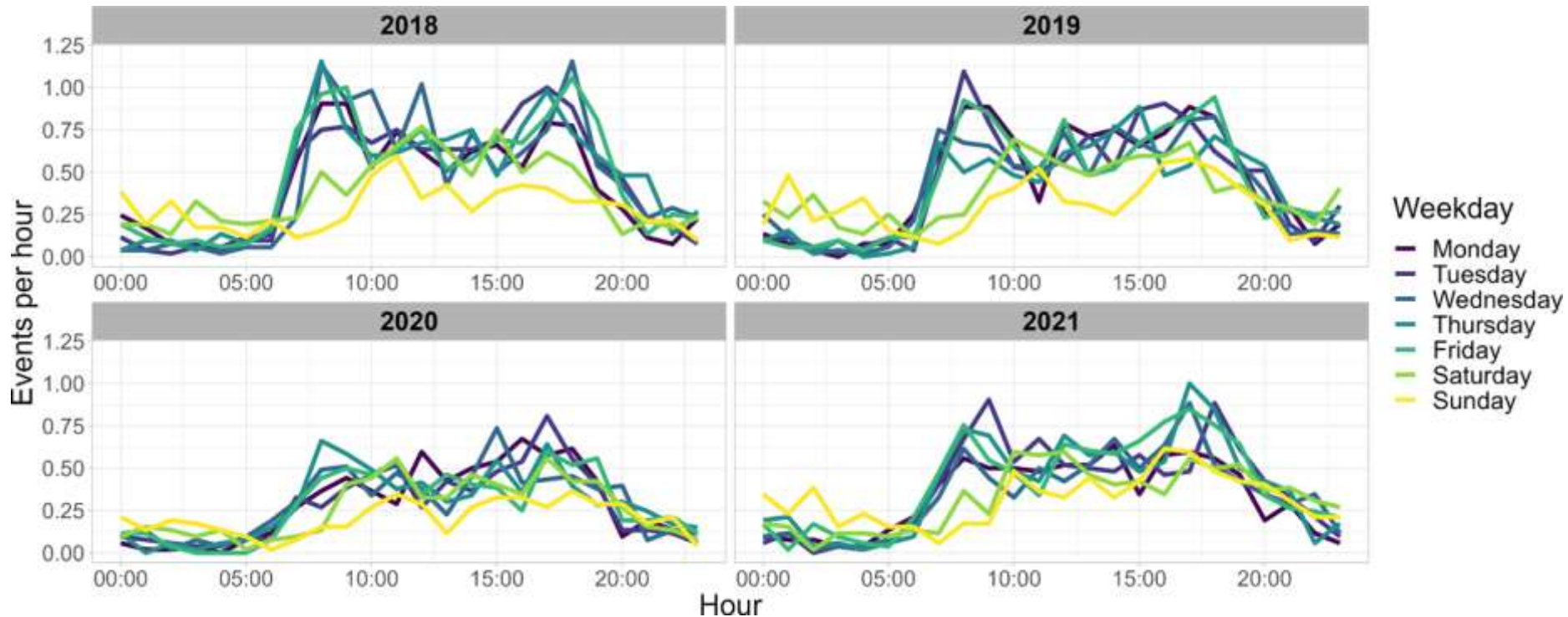
Temporal analysis - Via Olimpica



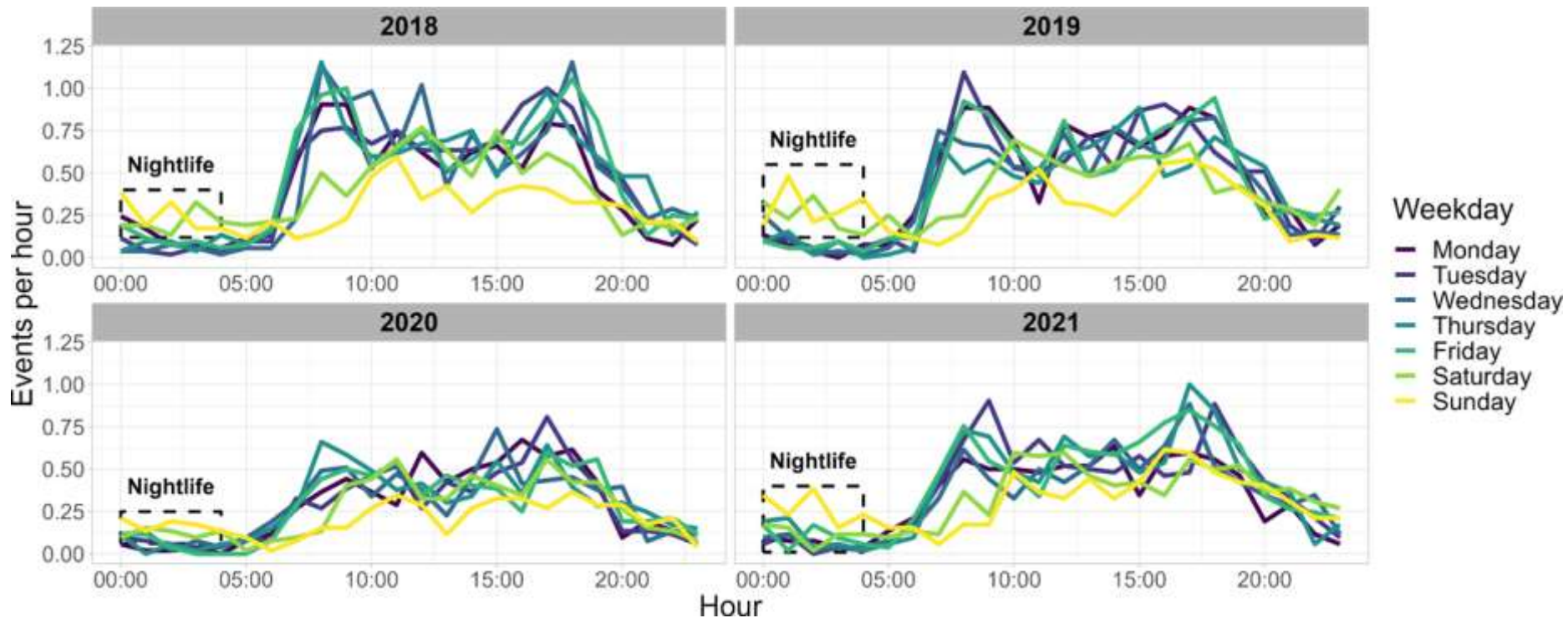
Temporal analysis - Via Olimpica



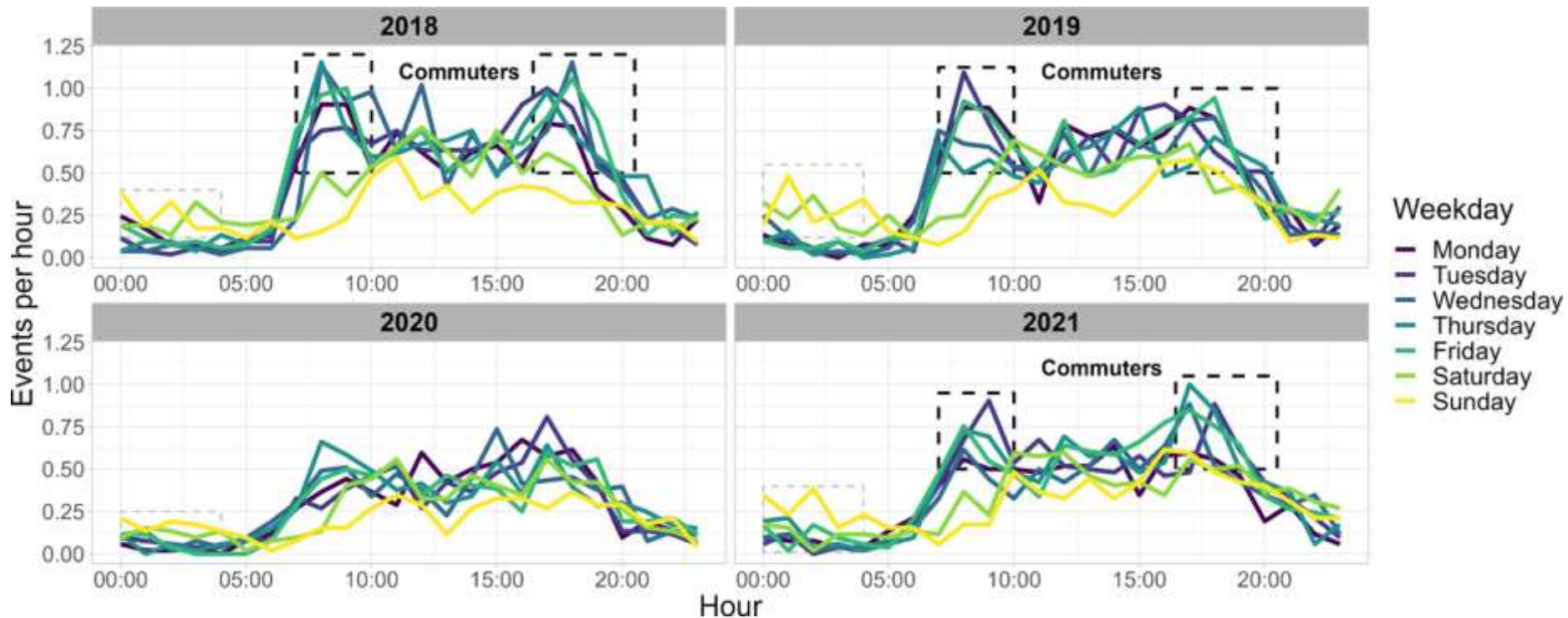
Temporal analysis - Via Olimpica



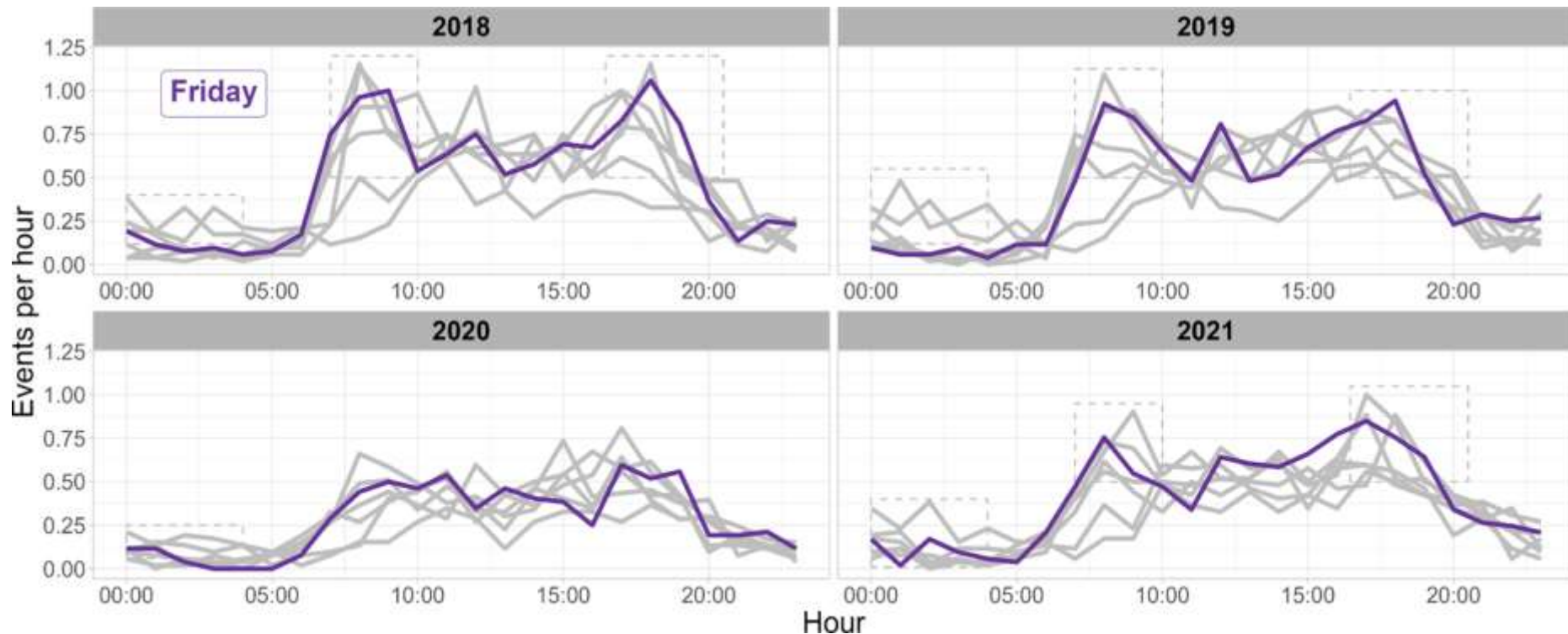
Temporal analysis - Via Olimpica



Temporal analysis - Via Olimpica

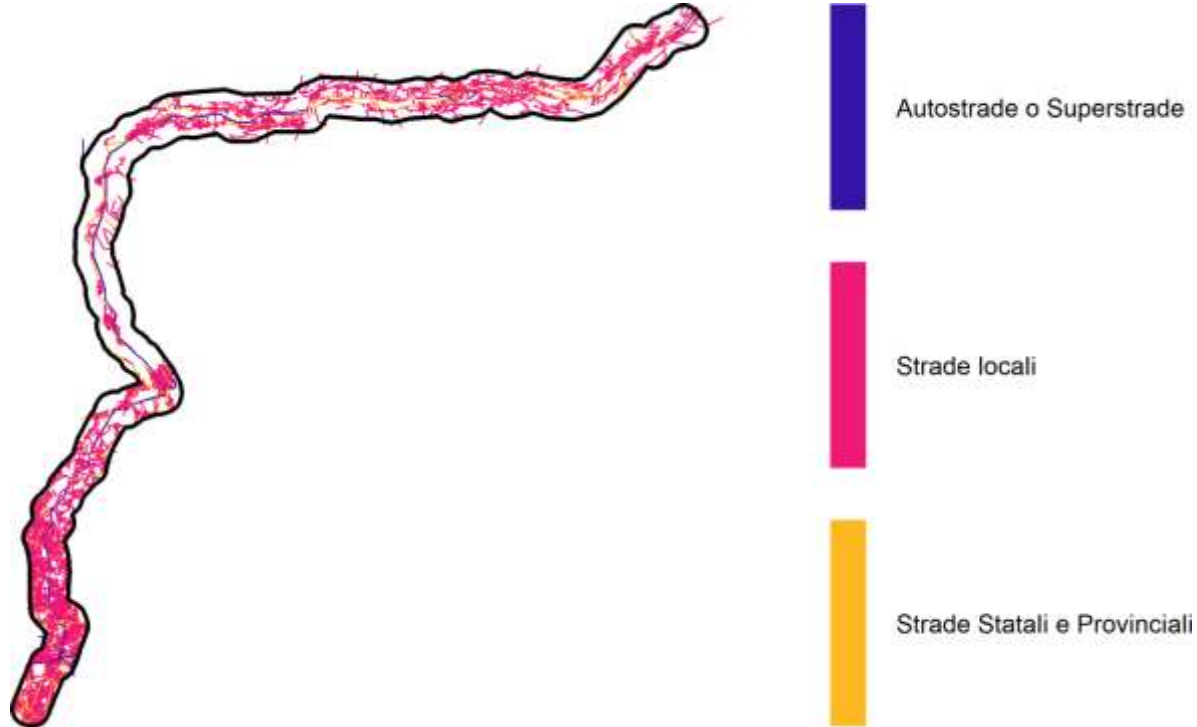


Temporal analysis - Via Olimpica



Deep dive on car crashes and road types

The main road (SS 36) is
classified as **Autostrada o
Superstrada!**



Deep dive on car crashes and road types

Ratio of car accident rates (Reference year: 2018)

2019	2020	2021
0.97 (0.95; 1.00)	0.65 (0.62; 0.68)	0.86 (0.82; 0.90)

Interpretation: On average, the number of car crashes per metre observed in 2020 is **65%** of that observed in 2018.

Deep dive on car crashes and road types

Ratio of car accident rates (Reference category: Autostrade)

	2018	2019	2020	2021
Strade Locali	0.55 (0.50; 0.61)	0.51 (0.45; 0.56)	0.68 (0.59; 0.77)	0.56 (0.50; 0.62)
Strade Statali e Provinciali	1.40 (1.26; 1.56)	1.16 (1.03; 1.29)	1.40 (1.21; 1.62)	1.25 (1.11; 1.42)

Interpretation: On average, the number of car crashes per metre observed in 2020 on *Strade Statali e Provinciali* is **140%** of that observed in *Autostrade e Superstrade* during the same year.